

PG (NEW) CBCS
M.Sc. Semester-II Examination, 2019
APPLIED MATHEMATICS WITH OCEANOLOGY AND
COMPUTER PROGRAMMING
PAPER: MTM-205
(GENERAL THEORY OF CONTINUUM MECHANICS)
Full Marks: 40 **Time: 2 Hours**

1. Answer any four questions of the following: **2×4**

- a) Find the relation between α and β such that the small deformation defined by $u_1 = \alpha x_1 + 3x_2$, $u_2 = x_1 - \beta x_2$ and $u_3 = 3x_3$ is isochronic.
- b) The components of a stress dyadic at a point referred to the (x_1, x_2, x_3) system are given by

$$(T_{ij}) = \begin{pmatrix} 12 & 9 & 0 \\ 9 & -12 & 0 \\ 0 & 0 & 6 \end{pmatrix}$$

For this state of stress, determine the maximum shear stress.

- c) Show that the difference between two values of a stream function at two points represents the flux of a fluid across any curve joining these two points.
- d) Differentiate between stream line and path line.
- e) Show that the extension of a strain quadric in the direction of any central radius vector is equal to the inverse of the square of the radius vector.
- f) State the Hooke's law for linear elastic material.
- g) Define principal direction and principal strain.
- h) Define steady fluid motion.

2. Answer any four questions of the following: **4×4**

- a) The displacement field for small deformation is given by

$$u_1 = (X_1 - X_3)^2 \quad u_2 = (X_2 + X_3)^2 \quad u_3 = -X_1 X_2$$

Determine rotation tensor and rotation vector at the point $(0, 2, -1)$.

(Turn over)

(2)

b) For the following stress distribution

$$(T_{ij}) = \begin{pmatrix} x^1 + x^2 & T_{12} & 0 \\ T_{12} & x^1 - 2x^2 & 0 \\ 0 & 0 & x^2 \end{pmatrix}$$

Find $T_{12}(x_1, x_2)$ in order that stress distribution is in equilibrium with zero body force and the stress vector on $x_1 = 1$ is given by

$$\vec{T}^n = (1 + x^2)\vec{e}_1 + (2 - x^2)\vec{e}_2$$

- c) “The rotation in a fluid can be measured by $\nabla \times \vec{V}$ where \vec{V} be the velocity of the fluid”- Explain it.
- d) Show that the principal directions of strain at each point in a linearly elastic isotropic body must be coincident with the principal directions of stress.
- e) Establish the stress vector and stress tensor relationship.
- f) Prove that all principal strains are real.
- g) Prove that the pressure at a point in a perfect fluid has the same magnitude in every direction.
- h) Defining complex potential, fluid the complex potential for a doublet.

3. Answer any two questions of the following:

2×8

- a) Derive the maximum shearing strain at any point of the continuum in terms of principal strains at that point.
- b) i) Find the integral of the Euler equation of motion for perfect fluid stating necessary assumptions when the flow is rotational and steady.
ii) If $\Phi = (x_1 - t) - (x_2 - t)$ be the velocity potential of a two-dimensional irrotational motion of a continuum, then show that stream lines at time t are $(x_1 - t)^2 - (x_2 - t)^2 = \text{constant}$
- c) Derive the basic elastic constants for isotropic elastic solid.
- d) State and prove the Kelvins Minimum Energy theorem for a perfect fluid.

PG (NEW) CBCS
M.Sc. Semester-II Examination, 2019
APPLIED MATHEMATICS WITH OCEANOLOGY AND
COMPUTER PROGRAMMING
PAPER: MTM-205
(GENERAL THEORY OF CONTINUUM MECHANICS)
Full Marks: 40 **Time: 2 Hours**

1. Answer any four questions of the following: **2×4**

- a) Find the relation between α and β such that the small deformation defined by $u_1 = \alpha x_1 + 3x_2$, $u_2 = x_1 - \beta x_2$ and $u_3 = 3x_3$ is isochronic.
- b) The components of a stress dyadic at a point referred to the (x_1, x_2, x_3) system are given by

$$(T_{ij}) = \begin{pmatrix} 12 & 9 & 0 \\ 9 & -12 & 0 \\ 0 & 0 & 6 \end{pmatrix}$$

For this state of stress, determine the maximum shear stress.

- c) Show that the difference between two values of a stream function at two points represents the flux of a fluid across any curve joining these two points.
- d) Differentiate between stream line and path line.
- e) Show that the extension of a strain quadric in the direction of any central radius vector is equal to the inverse of the square of the radius vector.
- f) State the Hooke's law for linear elastic material.
- g) Define principal direction and principal strain.
- h) Define steady fluid motion.

2. Answer any four questions of the following: **4×4**

- a) The displacement field for small deformation is given by

$$u_1 = (X_1 - X_3)^2 \quad u_2 = (X_2 + X_3)^2 \quad u_3 = -X_1 X_2$$

Determine rotation tensor and rotation vector at the point $(0, 2, -1)$.

(2)

b) For the following stress distribution

$$(T_{ij}) = \begin{pmatrix} x^1 + x^2 & T_{12} & 0 \\ T_{12} & x^1 - 2x^2 & 0 \\ 0 & 0 & x^2 \end{pmatrix}$$

Find $T_{12}(x_1, x_2)$ in order that stress distribution is in equilibrium with zero body force and the stress vector on $x_1 = 1$ is given by

$$\vec{T}^n = (1 + x^2)\vec{e}_1 + (2 - x^2)\vec{e}_2$$

- c) “The rotation in a fluid can be measured by $\nabla \times \vec{V}$ where \vec{V} be the velocity of the fluid”- Explain it.
- d) Show that the principal directions of strain at each point in a linearly elastic isotropic body must be coincident with the principal directions of stress.
- e) Establish the stress vector and stress tensor relationship.
- f) Prove that all principal strains are real.
- g) Prove that the pressure at a point in a perfect fluid has the same magnitude in every direction.
- h) Defining complex potential, fluid the complex potential for a doublet.

3. Answer any two questions of the following:

2×8

- e) Derive the maximum shearing strain at any point of the continuum in terms of principal strains at that point.
- f) i) Find the integral of the Euler equation of motion for perfect fluid stating necessary assumptions when the flow is rotational and steady.
 ii) If $\Phi = (x_1 - t) - (x_2 - t)$ be the velocity potential of a two-dimensional irrotational motion of a continuum, then show that stream lines at time t are
 $(x_1 - t)^2 - (x_2 - t)^2 = \text{constant}$
- g) Derive the basic elastic constants for isotropic elastic solid.
- h) State and prove the Kelvins Minimum Energy theorem for a perfect fluid.
